

Nonlinear Optimization

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Prof. Eckstein

Homework 5: Optimality Conditions and Lagrange Multipliers

Note that homework assignment 4 was the take-home midterm, so this is assignment 5.

1. Suppose, for $i = 1, \dots, \ell$, that $C_i \subseteq \mathbb{R}^{p_i}$ are nonempty cones. Show that their Cartesian product $C_1 \times \dots \times C_\ell$ is a cone and that $(C_1 \times \dots \times C_\ell)^\circ = C_1^\circ \times \dots \times C_\ell^\circ$.
2. Take two vectors $a, b \in \mathbb{R}^m$ with $a < b$ (as usual, inequalities between vectors are understood to apply to every pair of corresponding components). Let Y_0 be the “box” set $\{y \in \mathbb{R}^m \mid a \leq y \leq b\}$.
 - (a) For any point $y_0 \in Y_0$, give expressions for the feasible direction cone $K_{Y_0}(y_0)$ and its polar, the normal cone $N_{Y_0}(y_0)$.
 - (b) For some continuously differentiable function $g : \mathbb{R}^n \rightarrow \mathbb{R}^m$, consider the constraint system $X = \{x \in X_0 \mid g(x) \in Y_0\}$ with $X_0 = \mathbb{R}^n$, that is, let $X = \{x \in \mathbb{R}^n \mid g(x) \in Y_0\}$. Show that if the gradients $\nabla g_1(x_0), \dots, \nabla g_m(x_0)$ are linearly independent, then the system X is metrically regular at $x_0 \in \mathbb{R}^n$ (note: this simple condition is much stronger than necessary).
 - (c) Suppose we know that $\nabla g_1(x), \dots, \nabla g_m(x)$ are linearly independent for all $x \in \mathbb{R}^n$. Derive a set of necessary local optimality conditions for the optimization problem

$$\begin{array}{ll} \min & f(x) \\ \text{ST} & g(x) \in Y_0 \end{array} \quad \text{or equivalently} \quad \begin{array}{ll} \min & f(x) \\ \text{ST} & a \leq g(x) \leq b. \end{array}$$

There should m Lagrange multipliers. You may use without proof that finitely generated cones in \mathbb{R}^n are closed.

3. A *simplex* is a set of the form $S(R) = \{x \in \mathbb{R}^n \mid x \geq 0, x_1 + \dots + x_n = R\}$, for some $R > 0$. Consider the problem of projecting an arbitrary point $y \in \mathbb{R}^n$ onto $S(R)$:

$$\begin{array}{ll} \min & \frac{1}{2} \|x - y\|^2 \\ \text{ST} & \sum_{i=1}^n x_i = R \\ & x \geq 0 \end{array}$$

- (a) Considering the problem as having $X_0 = \mathbb{R}^n$ and treating the constraints $x \geq 0$ as being of the form $g(x) \leq 0$, show that this problem satisfies a constraint qualification.
- (b) Write the Karush-Kuhn-Tucker (KKT) conditions for this problem, using multipliers $\lambda_i \geq 0$, $i = 1, \dots, n$ for the constraints $x \geq 0$, and a single multiplier μ for the constraint $x_1 + \dots + x_n = R$. **Note: problem continues overleaf.**

- (c) Show that once one chooses μ , the KKT conditions uniquely determine the values of x_i and λ_i , $i = 1, \dots, n$.
- (d) Devise an algorithm to find the correct value of μ by sorting the elements y_i of y and then doing $O(n)$ additional work (“ $O(n)$ ” means “bounded by something proportional to n ”). *Instructor’s note: careful analysis of the complexity of this problem, drawing on the theory of linear-time median finding, can remove the necessity of fully sorting the elements of y , and reduces the entire solution complexity to $O(n)$; however, this refinement involves techniques beyond the scope of this course.*
- (e) Write a MATLAB program implementing your algorithm (MATLAB’s `sort` function will sort a vector). Hand in a printout of the `.m`-file of your function and its output x in the following cases:
- i. $n = 2, y = (1, 2), R = 2$
 - ii. $n = 2, y = (-1, 2), R = 2$
 - iii. $n = 4, y = (-1, 2, 3, 4), R = 5$
 - iv. $n = 4, y = (-1, 2, 3, 4), R = 3$
 - v. $n = 4, y = (4, 3, -1, 2), R = 3$
 - vi. $n = 4, y = (-1, -10, 8, 10), R = 16$